

Local Model Checking of Weighted CTL with Upper-Bound Constraints

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Introduction

- Model checking *both* functional and quantitative properties.
 - Embedded systems - resources are very limited.
 - Resource constraints: cost, memory, bandwidth, power, etc.
- We extend well-known models and temporal logic:
 - *Weighted* CTL & weighted Kripke structures.
- Efficient model checking of WCTL:
 - *Symbolic* dependency graphs
 - Local/on-the-fly fixed-point algorithm

Outline

- Weighted Model Checking
- Dependency graphs
- Symbolic dependency graphs
- Experiments
- Conclusion

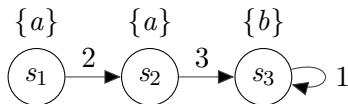
Weighted Kripke Structure

Definition (WKS)

A WKS is a tuple $\mathcal{K} = (S, \mathcal{AP}, L, \rightarrow)$, where

- S is a finite set of states,
- \mathcal{AP} is a set of atomic propositions,
- $L : S \rightarrow \mathcal{P}(\mathcal{AP})$ is a labelling function, and
- $\rightarrow \subseteq S \times \mathbb{N}_0 \times S$ is a transition relation.

Example



Weighted Computation Tree Logic (WCTL)

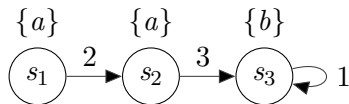
The set of WCTL formulas is given as follows.

$\varphi ::= true \mid false$	(Boolean Properties)
a	(Atomic Proposition)
$\varphi_1 \wedge \varphi_2$	(Conjunction)
$\varphi_1 \vee \varphi_2$	(Disjunction)
$E \varphi_1 U_{\leq k} \varphi_2$	(Existential Until)
$A \varphi_1 U_{\leq k} \varphi_2$	(Universal Until)
$EX_{\leq k} \varphi$	(Existential Next)
$AX_{\leq k} \varphi$	(Universal Next)

where $k \in \mathbb{N}_0$ and $a \in \mathcal{AP}$.

Semantics of the Until Modality

Example



We have that

$$s_1 \models E a U_{\leq 8} b$$

$$s_1 \not\models E a U_{\leq 4} b$$

Consider the only run

$$\sigma = \underbrace{s_1 \xrightarrow{2} s_2 \xrightarrow{3} s_3}_{\substack{\text{a holds} \\ \text{b holds}}} \xrightarrow{1} s_3 \dots$$

Accumulated weight $2 + 3 = 5$

Dependency Graph (1)

Definition (Dependency Graph)

A DG is a pair $G = (V, E)$, where

- V is a set of configurations, and
 - $E \subseteq V \times \mathcal{P}(V)$ is a set of hyper-edges.
-
- An assignment is a mapping $A : V \rightarrow \{1, 0\}$
 - A_{min} is the minimum fixed-point assignment.

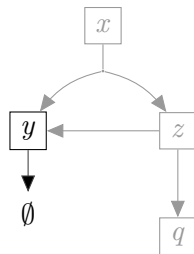
$A_{min}(u) = 1$ if there is $(u, T) \in E$ s.t.
for all $v \in T$ we have $A_{min}(v) = 1$.

Functor

$$F(A)(u) = \bigvee_{(u, T) \in E} \left(\bigwedge_{v \in T} A(v) \right)$$

$A_{min} = F(F(\dots F(A_0)))$ where $A_0(v) = 0$

Example



$A_{min}(y) = 1$ as $(y, \emptyset) \in E$

Dependency Graph (2)

Definition (Dependency Graph)

A DG is a pair $G = (V, E)$, where

- V is a set of configurations, and
 - $E \subseteq V \times \mathcal{P}(V)$ is a set of hyper-edges.
-
- An assignment is a mapping $A : V \rightarrow \{1, 0\}$
 - A_{min} is the minimum fixed-point assignment.

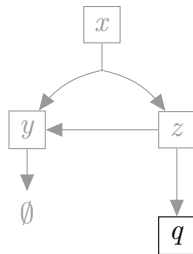
$A_{min}(u) = 1$ if there is $(u, T) \in E$ s.t.
for all $v \in T$ we have $A_{min}(v) = 1$.

Functor

$$F(A)(u) = \bigvee_{(u, T) \in E} \left(\bigwedge_{v \in T} A(v) \right)$$

$A_{min} = F(F(\dots F(A_0)))$ where $A_0(v) = 0$

Example



$$A_{min}(q) = 0$$

Dependency Graph (3)

Definition (Dependency Graph)

A DG is a pair $G = (V, E)$, where

- V is a set of configurations, and
 - $E \subseteq V \times \mathcal{P}(V)$ is a set of hyper-edges.
-
- An assignment is a mapping $A : V \rightarrow \{1, 0\}$
 - A_{min} is the minimum fixed-point assignment.

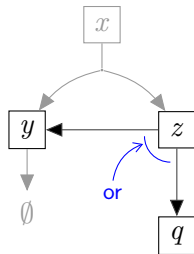
$A_{min}(u) = 1$ if there is $(u, T) \in E$ s.t.
for all $v \in T$ we have $A_{min}(v) = 1$.

Functor

$$F(A)(u) = \bigvee_{(u, T) \in E} \left(\bigwedge_{v \in T} A(v) \right)$$

$A_{min} = F(F(\dots F(A_0)))$ where $A_0(v) = 0$

Example



$$A_{min}(z) = A_{min}(y) \vee A_{min}(q)$$

Dependency Graph (4)

Definition (Dependency Graph)

A DG is a pair $G = (V, E)$, where

- V is a set of configurations, and
 - $E \subseteq V \times \mathcal{P}(V)$ is a set of hyper-edges.
-
- An assignment is a mapping $A : V \rightarrow \{1, 0\}$
 - A_{min} is the minimum fixed-point assignment.

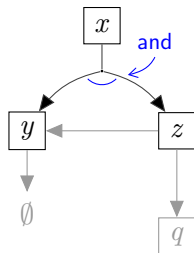
$A_{min}(u) = 1$ if there is $(u, T) \in E$ s.t.
for all $v \in T$ we have $A_{min}(v) = 1$.

Functor

$$F(A)(u) = \bigvee_{(u, T) \in E} \left(\bigwedge_{v \in T} A(v) \right)$$

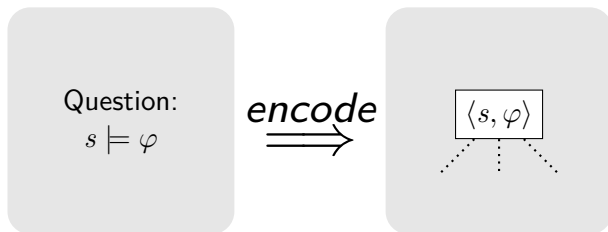
$A_{min} = F(F(\dots F(A_0)))$ where $A_0(v) = 0$

Example



$$A_{min}(x) = A_{min}(y) \wedge A_{min}(z)$$

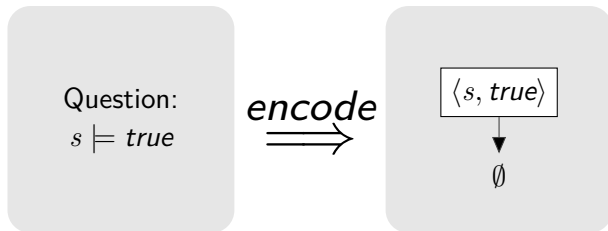
WCTL Model Checking with Dependency Graphs



Theorem 2

$$s \models \varphi \quad \Leftrightarrow \quad A_{min}(\langle s, \varphi \rangle) = 1$$

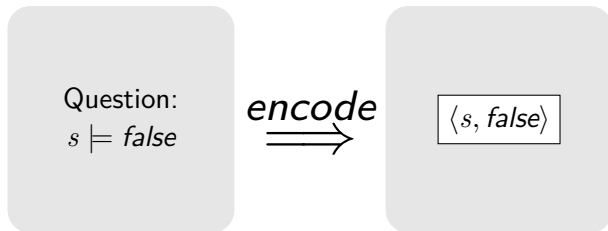
Encoding Example ($\varphi = \text{true}$)



We have the vacuous case, $A_{\min}(u) = 1$ for all u in \emptyset , hence

$$A_{\min}(\langle s, \text{true} \rangle) = 1$$

Encoding Example ($\varphi = \mathit{false}$)

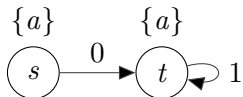


We have the trivial case, as $\langle s, \mathit{false} \rangle$ has no hyper-edges, hence

$$A_{\min}(\langle s, \mathit{false} \rangle) = 0$$

Model Checking Example

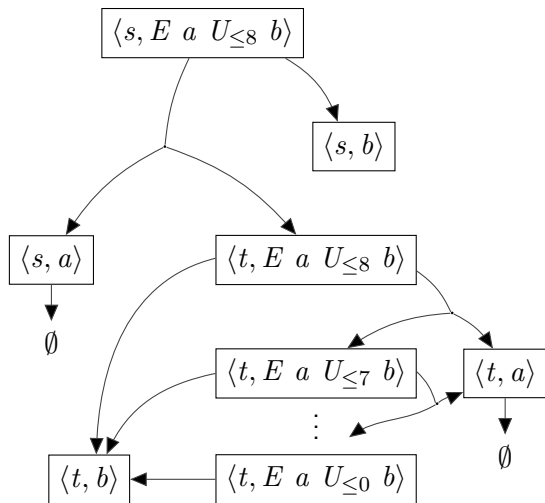
If we take the WKS



and want to determine if

$$s \models E a U_{\leq 8} b$$

we can encode this as:



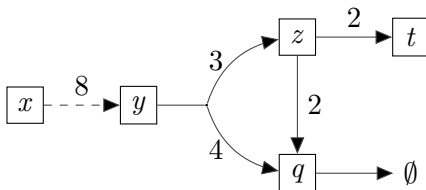
Symbolic Dependency Graphs

Definition (Symbolic Dependency Graphs)

An SDG is a triple $G = (V, H, C)$, where

- V is a finite set of configurations,
- $H \subseteq V \times \mathcal{P}(\mathbb{N}_0 \times V)$ is a finite set of hyper-edges, and
- $C \subseteq V \times \mathbb{N}_0 \times V$ is a finite set of cover-edges.

Example



Fixed-Point A_{min} of an SDG (1)

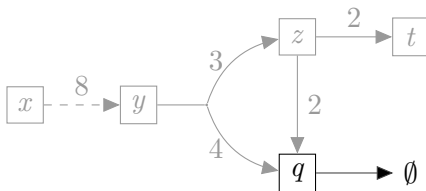
An assignment is a mapping $A : V \rightarrow \mathbb{N}_0 \cup \{\infty\}$

Functor for minimum fixed-point A_{min}

$$F(A)(u) = \begin{cases} 0 & \text{if } \exists (u, k, v) \in C \text{ s.t. } A(v) \leq k \\ \min_{(u, T) \in H} \left(\max\{w + A(v) \mid (w, v) \in T\} \right) & \text{otherwise.} \end{cases}$$

$A_{min} = F(\dots F(A_0))$ where $A_0(v) = \infty$.

Example



$$A_{min}(q) = 0 \text{ as } (q, \emptyset) \in E$$

Fixed-Point A_{min} of an SDG (2)

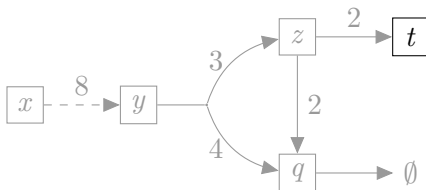
An assignment is a mapping $A : V \rightarrow \mathbb{N}_0 \cup \{\infty\}$

Functor for minimum fixed-point A_{min}

$$F(A)(u) = \begin{cases} 0 & \text{if } \exists (u, k, v) \in C \text{ s.t. } A(v) \leq k \\ \min_{(u, T) \in H} \left(\max\{w + A(v) \mid (w, v) \in T\} \right) & \text{otherwise.} \end{cases}$$

$A_{min} = F(\dots F(A_0))$ where $A_0(v) = \infty$.

Example



$$A_{min}(t) = \infty$$

Fixed-Point A_{min} of an SDG (3)

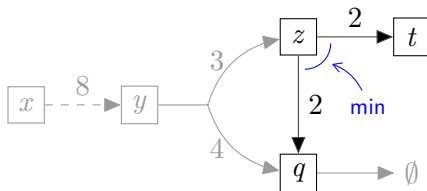
An assignment is a mapping $A : V \rightarrow \mathbb{N}_0 \cup \{\infty\}$

Functor for minimum fixed-point A_{min}

$$F(A)(u) = \begin{cases} 0 & \text{if } \exists (u, k, v) \in C \text{ s.t. } A(v) \leq k \\ \min_{(u, T) \in H} \left(\max\{w + A(v) \mid (w, v) \in T\} \right) & \text{otherwise.} \end{cases}$$

$A_{min} = F(\dots F(A_0))$ where $A_0(v) = \infty$.

Example



$$A_{min}(z) = \min(2 + A_{min}(q), 2 + A_{min}(t))$$

Fixed-Point A_{min} of an SDG (4)

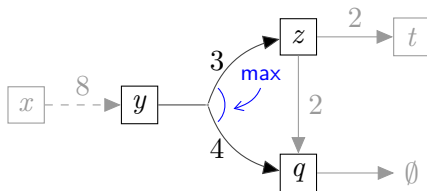
An assignment is a mapping $A : V \rightarrow \mathbb{N}_0 \cup \{\infty\}$

Functor for minimum fixed-point A_{min}

$$F(A)(u) = \begin{cases} 0 & \text{if } \exists (u, k, v) \in C \text{ s.t. } A(v) \leq k \\ \min_{(u, T) \in H} (\max\{w + A(v) \mid (w, v) \in T\}) & \text{otherwise.} \end{cases}$$

$A_{min} = F(\dots F(A_0))$ where $A_0(v) = \infty$.

Example



$$A_{min}(y) = \max(3 + A_{min}(z), 4 + A_{min}(q))$$

Fixed-Point A_{min} of an SDG (5)

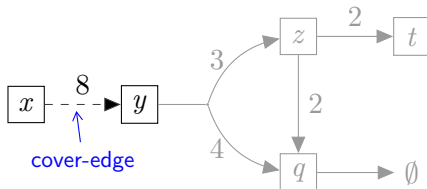
An assignment is a mapping $A : V \rightarrow \mathbb{N}_0 \cup \{\infty\}$

Functor for minimum fixed-point A_{min}

$$F(A)(u) = \begin{cases} 0 & \text{if } \exists(u, k, v) \in C \text{ s.t. } A(v) \leq k \\ \min_{(u, T) \in H} \left(\max\{w + A(v) \mid (w, v) \in T\} \right) & \text{otherwise.} \end{cases}$$

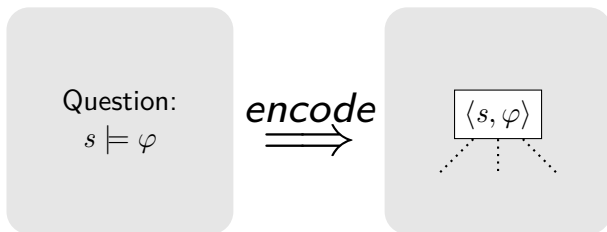
$A_{min} = F(\dots F(A_0))$ where $A_0(v) = \infty$.

Example



$$A_{min}(x) = \begin{cases} 0 & \text{if } A_{min}(y) \leq 8 \\ \infty & \text{otherwise} \end{cases}$$

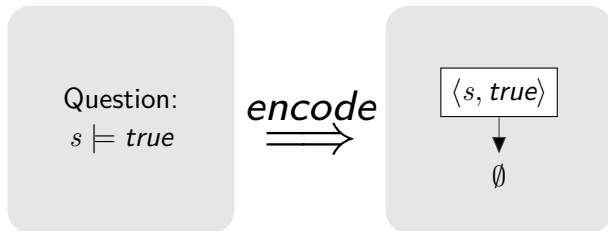
WCTL Model Checking with SDGs



Theorem 5

$$s \models \varphi \quad \Leftrightarrow \quad A_{min}(\langle s, \varphi \rangle) = 0$$

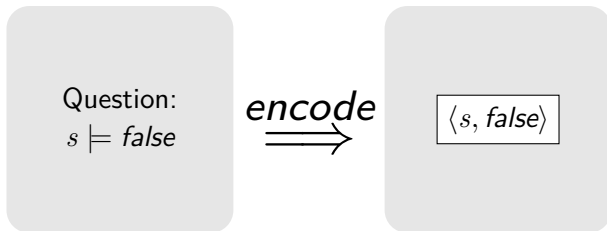
Encoding Example ($\varphi = \text{true}$)



We have the empty target-set and $\max(\emptyset) = 0$, hence

$$A_{\min}(\langle s, \text{true} \rangle) = 0$$

Encoding Example ($\varphi = \text{false}$)

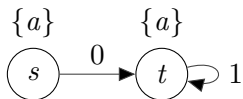


We have the trivial case, as $\langle s, \text{false} \rangle$ has no hyper-edges, hence

$$A_{\min}(\langle s, \text{false} \rangle) = \infty$$

Model Checking with SDG Example

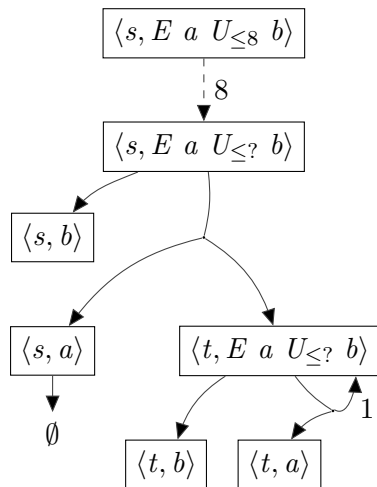
If we take the WKS



and want to determine if

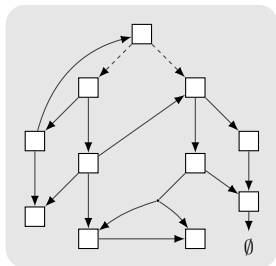
$$s \models E a U_{\leq 8} b$$

then we can encode this as:



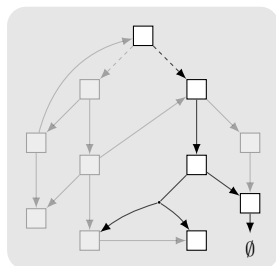
Fixed-Point Algorithms

Global



- Up-front construction of SDG.
- Repeated application of F .
- Terminates with A_{min} for all configurations.

Local



- On-the-fly construction of SDG.
- Top-down w. backwards propagation.
- Terminates with A_{min} for the initial configuration.

Model Checking with WKTool

WKTool
Save Load Delete Export Visualize Help

```

5 # <rack0>      Medium  Sender  Receive ack x
6 # <rx>         Medium  Receiver Receive x
7 # <acks>       Receive  Medium  Send ack x
8 # <deliver>
9
10 # Sender
11 Sender := Ready0;
12 Ready0 := <send>.Sending0;
13 Ready1 := <send>.Sending1 + Oops;
14 Sending0 := <transmit!>.send0:(<rack0>.Ready1 + <rack1>.Sending0 + <tau>.Sending0);
15 Sending1 := <transmit!>.send1:(<rack1>.Ready0 + <rack0>.Sending1 + <tau>.Sending1);
16
17 # Receiver
18 Receiver := Receive0;

```

TypeError, Line 13, Column 31: Process constant "Oops" isn't defined

Status	State	Formula	Time
✓	System	! We can have 1 messages delive... EF (<= 4) delivered == 1	83 ms
✗	System	! We deliver the same bit that ... AG delivered (!send0 A !s...	21 ms

Formula Is Satisfiable

Cover-edges	1
Hyper-edges	5720
Configurations	2551
Iterations	11115
Queue size	, max 915
Search strategy	Depth First Search
Encoding / Engine	Symbolic / Local

Edit Property

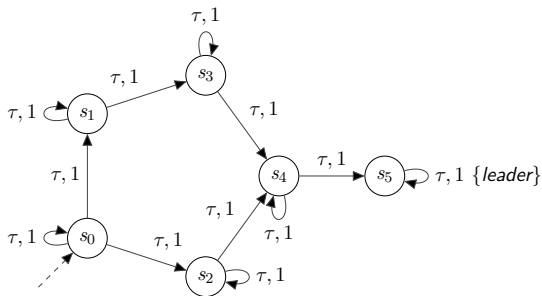
<http://wktool.jonasfj.dk/>

Experiments

Evaluation of DG vs. SDG and local vs. global for SDG.

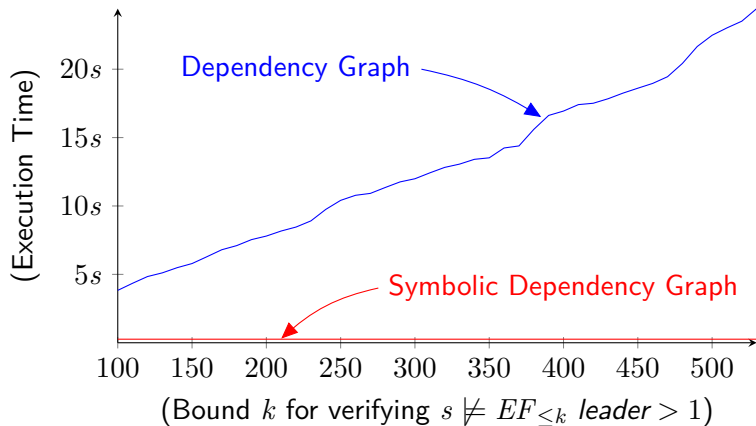
Models:

- Leader Election
- Alternating Bit Protocol
- Task Graph Scheduling problems for 2 processors



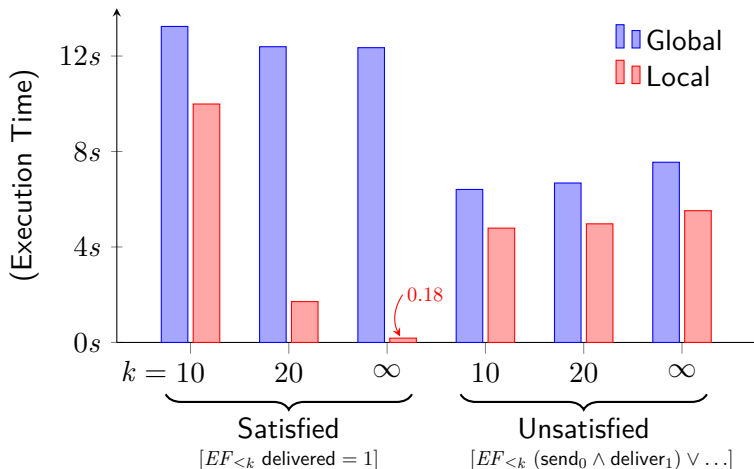
Direct vs. Symbolic (Scaling Bound)

Leader election with DG and SDG encodings using global algorithms.

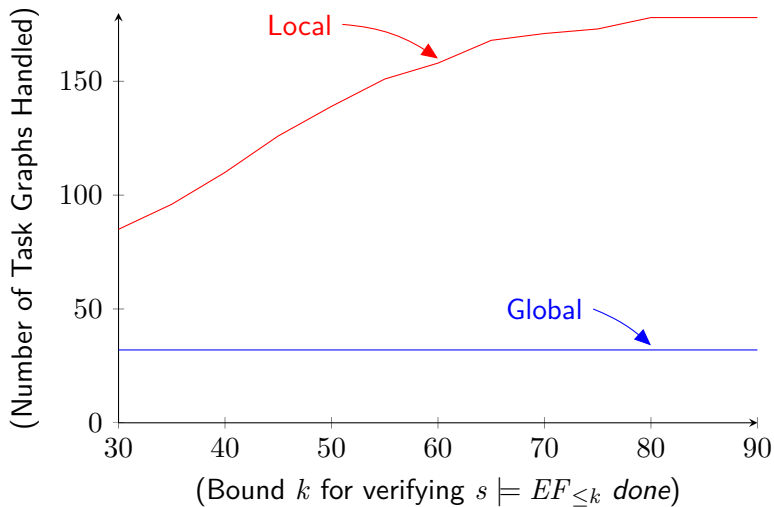


Comparing Global and Local for SDGs

Alternating bit protocol with buffer size 9 (satisfied) and 8 (unsatisfied).

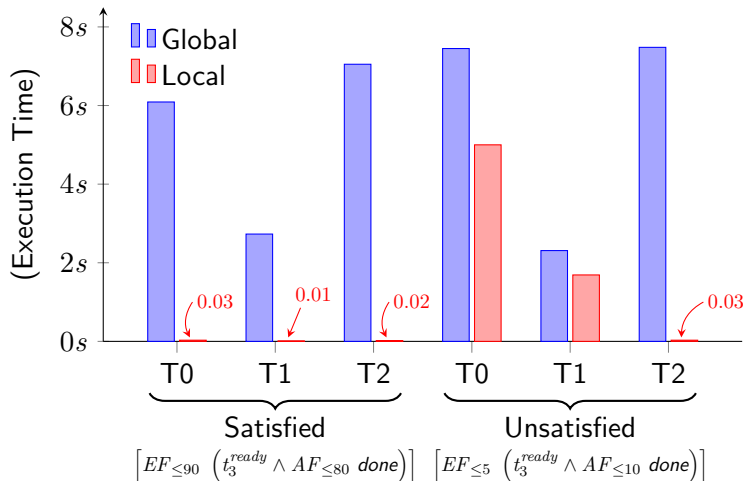


Global vs. Local on 180 Task Graphs

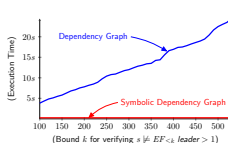


Comparing Global and Local for SDGs

Task graphs T0, T1 and T2 with 5 tasks and nested WCTL properties.

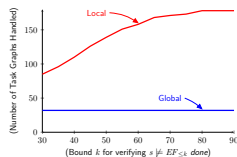


Conclusion



Symbolic Dependency Graphs are advantageous for weighted model checking

Local algorithm can handle larger problems



Future work:

- Alternating fixed-points for *full* WCTL logic.
- Lower-bound constraints on temporal operators.
- Heuristics for search strategy.